Switching phenomena in magnetic vortex dynamics

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A magnetic nanoparticle in a vortex state is a promising candidate for information storage. One bit of information corresponds to the upward or downward magnetization of the vortex core (vortex polarity). The generic properties of the vortex polarity switching are insensitive to the way that the vortex dynamics has been excited: by an ac magnetic field, or by an electrical current. We study theoretically the switching process and describe in detail its mechanism, which involves the creation and annihilation of an intermediate vortex-antivortex pair. © 2008 American Institute of Physics. [DOI: 10.1063/1.2957013]

INTRODUCTION

Artificial mesoscopic magnetic structures now provide a wide testing area for concepts of nanomagnetism and numerous prospective applications.1,2 Investigations of magnetic nanostructures include studies of magnetic nanodots, which are submicron disk-shaped particles, which have a single vortex in the ground state due to the competition between the exchange and magnetic dipole-dipole interactions.3 A vortex state is obtained in nanodots that are larger than a single domain whose size is a few nanometers: e.g., for a Permalloy (Ni80Fe20) nanodot the exchange length\(\ell\approx 5\) nm. Having nontrivial topological structure on the scale of a nanomagnet, the magnetic vortex is a promising candidate for the high-density magnetic storage and high-speed magnetic random access memory.\(^3\) For this one needs to control magnetization reversal, a process in which vortices play a big role.\(^4\) Great progress has been made recently with the possibility of observing the high-frequency dynamical properties of the vortex state in magnetic dots by the Brillouin light-scattering of spin waves,\(^5,6\) time-resolved Kerr microscopy,\(^7\) phase-sensitive Fourier transformation technique,\(^8\) x-ray imaging technique,\(^9\) and micro-SQUID technique.\(^10\)

The control of magnetic nonlinear structures using an electrical current is of special interest for applications in spintronics.\(^11,12\) The spin torque effect, which is the change of magnetization due to the interaction with an electrical current, was predicted by Slonczewski\(^13\) and Berger\(^14\) in 1996. During the last decade this effect was tested in different magnetic systems\(^15-17\) and nowadays it plays an important role in spintronics.\(^11,18\) Recently the spin torque effect was observed in vortex-state nanoparticles. In particular, circular vortex motion can be excited by an ac\(^19\) or a dc\(^20\) spin-polarized current. Very recently it was predicted theoretically\(^21,22\) and observed experimentally\(^23\) that the vortex polarity can be controlled using a spin-polarized current. This opens up the possibility of realizing electrically controlled magnetic devices, changing the direction of modern spintronics.\(^24\)

The basics of the magnetic vortex\(^25\) statics and dynamics in Heisenberg magnets was studied in 1980s, in particular by the group of Kosevich.\(^27-29\) Typically, the vortex is considered as a rigid particle without internal degrees of freedom; such a vortex undergoes a so-called gyroscopic dynamics in the framework of Thiele-like equations.\(^30-32\) Using a rigid vortex dynamics a number of dynamical effects were studied; see Ref. 33 for a review. Cycloidal oscillations around the mean vortex trajectory can be explained by taking into account the changes of the vortex shape due to its velocity.\(^33,34\)

The rigid approach also fails when considering the vortex dynamics under the influence of a strong or fast external force. In particular, it is known that external pumping excites internal modes in vortex dynamics in Heisenberg magnets, whose role is important for understanding switching phenomena\(^35-39\) and the limit cycles in vortex dynamics.\(^40,41\)

Very recently we have found that under the action of a magnetic field, or, alternatively, under the action of a spin current on a vortex state nanodot, the vortex core magnetization (polarity) can be switched. This effect was studied in Ref. 21 analytically and confirmed numerically by direct spin-lattice simulations for Heisenberg magnets. However, the presence of the long-range dipolar interaction crucially changes the vortex dynamics,\(^22\) because this interaction creates an effective inhomogeneous anisotropy.\(^21,47,48\) The goal of this paper is to consider the generic properties of polarity switching in magnetic nanodots.

MODEL AND EQUATIONS OF MOTION

The magnetic energy of nanodots consists of two parts: Heisenberg exchange and dipolar interactions:
\[
\mathcal{H} = -\frac{\ell^2}{2} \sum_{\mathbf{n}, \mathbf{\delta}} S_{\mathbf{n}} \cdot S_{\mathbf{n+\delta}} + \frac{1}{8\pi} \sum_{\mathbf{n}, \mathbf{n'}} \frac{S_{\mathbf{n}} \cdot S_{\mathbf{n'}} - 3(S_{\mathbf{n}} \cdot \mathbf{e}_{\mathbf{n}})(S_{\mathbf{n'}} \cdot \mathbf{e}_{\mathbf{n'}})}{|n - n'|^3}.
\]

Here \( S_{\mathbf{n}} \) is a unit vector which determines the spin direction at the lattice point \( \mathbf{n} \), \( \ell = \sqrt{A/(\mu_0 M_S^2)} \) is the exchange length \( A \) is the exchange constant, \( \mu_0 \) is the vacuum permeability, \( M_S \) is the saturation magnetization, \( \mathbf{e}_{\mathbf{n}} \) connects nearest neighbors, and \( \mathbf{e}_{\mathbf{n}} = (n - n')/|n - n'| \) is a unit vector.

The lattice constant is chosen as the unit of length.

\[
\mathbf{S}_n = -\mathbf{S}_n \times \frac{\partial \mathcal{H}}{\partial \mathbf{S}_n} - \alpha \mathbf{S}_n \times \mathbf{S}_n + \mathbf{S}_n \times \mathbf{b}_n. \tag{2}
\]

Here the overdot indicates the derivative with respect to the dimensionless time \( \tau = \omega t \) with \( \omega_0 = 4\pi \gamma M_S \), and \( \alpha < 1 \) is a damping coefficient. The last term is a spin torque due to external forces, which results in a magnetic field \( \mathbf{b}_n \). In the presence of the uniform rotating field \( \mathbf{B}(t) = (B \cos \omega t, B \sin \omega t, 0) \), the dimensionless field

\[
\mathbf{b} = b_x + i b_y = \frac{B}{4\pi M_S} \exp(i\omega t). \tag{3a}
\]

Here and below all frequencies are measured in units of \( \omega_0 \), and all distances in units of \( \ell \).

When an electrical current is injected into the pillar structure perpendicular to the nanodisk plane, it influences locally the spin \( \mathbf{S}_n \) of the lattice through the spin torque \( \mathbf{T}_n = \mathbf{S}_n \times \mathbf{b}_n \) (Refs. 13 and 14), where

\[
\mathbf{b}_n = j \sigma A \frac{\mathbf{S}_n \times \hat{z}}{1 + \sigma s \mathbf{S}_n \cdot \hat{z}}. \tag{3b}
\]

Here \( j = J_\perp / J_p \) is a normalized spin current, \( J_p \) is the electrical current density, \( J_p = \mu_0 M_S^2 e|\hbar|/\hbar \), \( e \) is the disk thickness, \( \hbar \) is the disk thickness, \( e \) is the electron charge,

\[
A = 4\eta_{sp}^{1/2} \left[ 3(1 + \eta_{sp})^3 - 16 \eta_{sp}^{3/2} \right],
\]

\[
B = (1 + \eta_{sp})^3/\left[ 3(1 + \eta_{sp})^3 - 16 \eta_{sp}^{3/2} \right],
\]

and \( \eta_{sp} \in (0; 1) \) denotes the degree of spin polarization; \( \sigma = \pm 1 \) gives two directions of the spin-current polarization.

\begin{equation}
\mathcal{E} = \int d^2x \left[ \frac{\ell^2}{2} (\nabla \cdot \mathbf{m})^2 - \frac{\mathbf{m} \cdot \mathbf{H}^{\text{ext}}}{2} - \mathbf{m} \cdot \mathbf{b} \right],
\end{equation}

where \( \mathbf{H}^{\text{ext}} \) is the normalized magnetostatic field, which comes from the dipolar interaction. \( \xi \) is Eq. (4) we suppose that the magnetization distribution does not depend on the \( z \) component (which is valid for thin disks), and we have normalized the energy by the disk thickness \( h \).

Let us consider a cylindric nanoparticle of top surface radius \( L \) and thickness \( h \). For small size nanoparticles the ground state is uniform; it depends on the particle aspect ratio \( e = h/(2L) \); thin nanodisks are magnetized in the plane (when \( e < e_c \approx 0.96; \text{Ref. 43} \)) and thick ones along the axis (when \( e > e_c \)). When the particle size exceeds some critical value, typically \((3-4)\ell\), curling of the magnetization becomes energetically preferable due to the competition between the exchange and dipolar interactions. For a disk-shaped particle the vortex state appears. For thin enough disks the vortex structure does not depend on the \( z \) coordinate of the disk, and the magnetization distribution for a vortex situated at the disk center is determined by the expressions\(^{33}\)

\[
\cos \theta = p f(\zeta), \quad \varphi = q \arg(\zeta + C\pi/2).
\]

Here \( \zeta = x + iy \) is the coordinate in the disk plane, \( q = +1 \) is the vortex \( \pi_1 \) topological charge (vorticity), \( C = \pm 1 \) characterizes the vortex chirality, and \( p = \pm 1 \) determines the direction of the vortex core magnetization (polarity). The bell-shaped function \( f(\zeta) \) describes the vortex core magnetization. The vortex polarity is connected to the \( \pi_2 \) topological properties of the system,\(^{32,33}\) the Pontryagin index\(^{28,29}\)

\[
Q = \frac{1}{8\pi} \int d^2x \left[ \partial_x \mathbf{m} \times \partial_y \mathbf{m} \right].
\]

For the vortex configuration the Pontryagin index takes the half-integer values \( Q = \pm pq/2 \).

For the vortex solution localized at \( Z = X + iY \)

\[ R \exp(i\Phi), \] \( \Phi \) the field has the form \( \varphi = q \arg(\zeta - Z) + C\pi/2 \).

Such a form of the \( \varphi \) field satisfies Laplace’s equation, so it describes the planar vortex dynamics (neglecting the \( z \) component of magnetization) for the infinite Heisenberg magnets. The finite size effects for the circular Heisenberg magnet can be described by the image-vortex ansatz.\(^{33}\) Moreover, one has to take into account the long-range dipolar interactions, which lead in general to integro-differential equations.\(^{45}\) For a thin ferromagnet the dipolar interactions produce an effective uniaxial anisotropy of the easy-plane type caused by the facial surface magnetostatic charges\(^{46,47}\) and an effective in-plane anisotropy caused by the edge surface charges (surface anisotropy).\(^{37,48}\) Due to the surface anisotropy the magnetization near the disk edge is constrained.

\section*{VORTEX STRUCTURE AND RIGID VORTEX DYNAMICS}

In the case of weak dipolar interactions, the characteristic exchange length \( \ell \) is larger than the lattice constant \( a \), so that in the lowest approximation in the small parameter \( a/\ell \) and weak gradients of the magnetization \( \mathbf{m} = -(\mathbf{S}_n) = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta) \) we can use the continuum approximation for the Hamiltonian (1).

\[
\mathcal{E} = \int d^2x \left[ \frac{\ell^2}{2} (\nabla \cdot \mathbf{m})^2 - \frac{\mathbf{m} \cdot \mathbf{H}^{\text{ext}}}{2} - \mathbf{m} \cdot \mathbf{b} \right].
\]
to be tangential to the boundary, which prevents its precession near the edge (absence of surface charges).\textsuperscript{47,49,50} Finally, the $\varphi$ field can be written in the form

$$\varphi = \arg(\zeta - Z) + \arg(\zeta - Z') - \arg Z + C \pi \left(\frac{1}{2}\right).$$  

(5b)

Here $Z'=Z \pm Z^2/R^2$ is the image vortex coordinate; the image vortex is added to satisfy the Dirichlet boundary conditions.

Under the influence of an external force the vortex starts to move. If such forces are weak, the vortex behaves like a particle during its evolution. Such rigid vortex dynamics can be well described using the Thiele approach.\textsuperscript{30,31} Following this approach we use the traveling wave ansatz $m(r, \tau) = m(r - R(\tau))$, where the function $m$ on the right-hand side describes the vortex shape ($5a$) and ($5b$). This results in a force balance equation $F^x + F^y + F = 0$. The first term $F^x = -2Q[R \times \dot{z}]$ is a gyroscopical force,\textsuperscript{31,32} which acts on a moving vortex in the same way as the magnetic field influences a charged particle by the Lorentz force. The second term is a dissipative force $F^d = -\eta R$ with $\eta = (\alpha/2) \ln L$, and the last term is an external force $F = -(2\pi)^{-1} \nabla_{\mathbf{r}} E = F^{\text{ext}}$, where the total energy is described by Eq. (4). The magnetostatic part of this force is caused mainly by magnetostatic energy of volume charges. For small displacements $R \ll L$ from the disk origin and small aspect ratios ($\varepsilon \ll 1$), it can be found analytically\textsuperscript{51} that $F^{\text{ext}} = -\Omega_G R$, with $\Omega_G = 10\pi/9 \pi$.\textsuperscript{52} For finite $\varepsilon$ one can use the analysis in Refs. 53 and 54, which results in $\Omega_G(\varepsilon)$. Finally, the force balance condition takes the form of a Thiele equation

$$2Q[R \times \dot{z}] = F^{\text{ext}} - \eta R - \Omega_G R.$$  

(6)

Without dissipation and external force this equation describes the gyration of a vortex around the disk origin with a frequency $\Omega_G$. The dissipation damps the possible circular motion of the vortex. However, an external force can excite a nondecaying vortex motion. For example, it is known that the rotating magnetic field can excite a circular rotation of the vortex in a Heisenberg magnet\textsuperscript{40,41} and a nanomagnet\textsuperscript{55} due to the force\textsuperscript{41}

$$F^{\text{ext}} = -\frac{bl}{2R} \left[ R \cos(\Phi - \omega \tau) + [R \times \dot{z}] \sin(\Phi - \omega \tau) \right].$$  

(7a)

In the case of electrical current influence the circular vortex dynamics can be excited by the force\textsuperscript{56–58}

$$F^{\text{ext}} = \frac{j \sigma A q}{2 \omega_0} [R \times \dot{z}].$$  

(7b)

Note that the vortex motion can be excited by any small magnetic field ($b, \omega$)\textsuperscript{55} however, to excite the vortex motion by a spin current, its intensity must exceed a threshold value.\textsuperscript{57,58}

**NUMERICAL STUDIES**

To check the analytical predictions about the driven vortex dynamics, we have performed numerical simulations. In the case of a rotating magnetic field we used the micromagnetic simulator for Landau-Lifshitz-Gilbert equations\textsuperscript{59} as described in Ref. 55. To study the vortex dynamics under the action of a spin-polarized electrical current, we used numerical simulations of the discrete spin-lattice Eq. (2) with the spin torque given by Eq. (3b) as described in Refs. 22 and 58. In both cases, as the initial condition we use a vortex with positive polarity ($p = +1$), centered at the disk origin. To identify the vortex position precisely we use, similar to Ref. 60, the intersection of the isosurfaces $m_i = 0$ and $m_q = 0$.

Let us start with the case of a spin current. If we apply a current whose polarization is parallel to the vortex polarity ($j \sigma > 0$), the vortex does not quit the disk center, which is a stable point. However, if the spin current has the opposite direction of the spin polarization ($j \sigma < 0$, $p = +1$, $\sigma = +1$, and $j < 0$ in our case) the vortex motion can be excited when the current intensity is above a threshold value\textsuperscript{56–58} as a result of the balance between the pumping and damping. Following the spiral trajectory, the vortex finally reaches a circular limit cycle. The sense of rotation of the spiral is determined by the gyroforce, i.e., by the topological charge $Q$, which is a clockwise rotation in our case. At some value, the radius becomes comparable with the system size $L$ and the vortex dynamics becomes more complicated and can not be described by the Thiele equation (6). Finally, it results in a switching of the vortex core; see below.

A qualitatively similar picture is found in the case of a rotating field with angular frequency directed opposite to the vortex polarity: $\omega p < 0$. There exist different regimes in the vortex dynamics.\textsuperscript{55} In the range of frequencies close to the frequency of the orbital vortex motion ($\Omega \sim 1$ GHz) the vortex demonstrates a finite motion in a region near the disk center along a quite complicated trajectory and does not switch its polarity. These cycloidal vortex oscillations are similar to those in Ref. 34 and correspond to the excitation of higher magnon modes during the motion. If $\omega \gg \Omega$, then for weak fields the vortex motion can be considered as a sum of two constituents: (i) the gyroscopic orbital motion as without field, and (ii) cycloidal oscillations caused by the field influence. For the case $\omega p < 0$ the direction of the cycloidal oscillations coincides with the direction of the field rotation, while the direction of the gyroscopic orbital motion is opposite to it. For stronger fields the vortex motion becomes more complicated and its average motion can be directed even opposite to the gyroscopic motion (this situation is shown in Fig. 1). The irreversible switching of the vortex polarity can be excited in a specific range of parameters ($\omega, b$), with typical frequencies of about 10 GHz and intensities of about 20 mT.\textsuperscript{55} The mechanism of the switching is discussed below.

**VORTEX POLARITY SWITCHING**

The mechanism of the vortex switching is of a general nature; it is essentially the same in all systems where the switching has been observed.\textsuperscript{22,23,53,56,61–64} Under the action of pumping, the original vortex ($Q = 1, \sigma = 1, Q_V = 1/2$), situated at the center of the disk, moves along a spiral trajectory in the case of a current or along a more complicated trajectory (as described in the previous Section) in the case of the rotating field. During its motion, the vortex excites a number of spin waves.\textsuperscript{65} Mainly magnon modes of two kinds are excited in this system: symmetrical and azimuthal ones.\textsuperscript{36,39} Due to the continuous pumping, the system goes to the nonlinear regime: the amplitude of the azimuthal mode
increases and there appears an out-of-plane dip near the vortex; see Fig. 1a. When the amplitude of the out-of-plane dip reaches its minimum ($m_z = 1$; Fig. 1b) a pair of a new vortex \((N_V, q_{NV} = 1, p_{NV} = -1, Q_{NV} = -1/2)\) and antivortex \((\overline{A}_V, q_{AV} = -1, p_{AV} = -1, Q_{AV} = 1/2)\) is created. These three objects move following complicated trajectories which result from Thiele-like equations. The directions of the motion of the partners are determined by the competition between the gy-

**FIG. 1.** The vortex switching process under rotating field influence. Left column—vortex trajectories. Solid line—initial vortex core trajectory, dashed line—new vortex, dash-and dot-line—antivortex. Right column—in-plane magnetization distribution, the out-of-plane component is denoted by levels of gray color, the dashed and solid lines correspond to isosurfaces $m_x = 0$ and $m_y = 0$, respectively. The out-of-plane component $m_z$ is shown in the middle column. The data were obtained from micromagnetic simulation for a permalloy disk (132 nm diam., 20 nm thickness) dynamics under the influence of a rotating field \((B=0.07 \text{ T}, \omega = 10 \text{ GHz})\). KEY: $t=110$ ps: the rotating field causes the vortex motion, and, as a result a negative dip is forming. $t=320$ ps: a vortex-antivortex pair has been born in region 1. $t=420$ ps: the vortex pair has annihilated in region 2, and, after some time a new vortex-antivortex pair is born in region 3. $t=495$ ps: the new antivortex has annihilated with the old vortex in region 4, and only the new vortex of opposite polarity remains.
roscopical motion and the external forces, which are the magnetostatic force $\mathbf{F}^{\text{mst}}$, the pumping force $\mathbf{F}^{\text{ext}}$ [see Eqs. (7a) and (7b)], and the interactions between the vortices $\mathbf{F}^{\text{int}}$.

The magnetostatic force for the three-body system can be calculated, using the image vortex approach, which corresponds to fixed (Dirichlet) boundary conditions. For the vortex state nanodisk such boundary conditions result from the magnetostatic interaction, which is localized near the disk edge. The same statement is also valid for the three-vortex (V–AV–NV) state, as is confirmed also by our numerical simulations. The $\varphi$ field can be presented by the three-vortex ansatz

$$\varphi = \sum_{i=1}^{3} q_i [\arg(\zeta - Z_i) + \arg(\zeta - Z_i^*) - \arg Z_i] + C \frac{\pi}{2}. \quad (8)$$

The force coming from the volume magnetostatic charge density $\lambda = -\nabla \cdot \mathbf{m}$ can be calculated in the same way as for a single vortex, which results in $\mathbf{F}^{\text{mst}} = -\Omega C q_i \sum_j q_j \mathbf{R}_{ij}$, where $q_i = \pm 1$ is the vorticity of the $i$th vortex (antivortex).

The interaction force $\mathbf{F}^{\text{int}}$ between vortices is a 2D coulomb force

$$\mathbf{F}^{\text{int}}_{ij} = \sum_{i \neq j} q_i q_j \frac{\mathbf{R}_{ij}}{|\mathbf{R}_{ij}|^2}. \quad (9)$$

The internal gyroforces of the dip impart the initial velocities to the NV and AV, which are perpendicular to the initial dip velocity and have opposite directions. In this way the AV gains a velocity component directed to the center, and the NV has opposite velocities to the NV and AV, which are perpendicular to the initial dip velocity. This newborn pair is a topologically trivial pair, which undergoes a Kelvin motion. This Kelvin pair collides with the original vortex. If the pair was born far from V then the scattering process is semielastic; the newborn pair is not destroyed by the collision. In the exchange approach this pair survives, but it is scattered by some angle. Due to additional forces (pumping, damping and magnetostatic interaction), the real motion is more complicated, and the Kelvin pair can finally annihilate by itself; see Fig. 1c.

Another collision mechanism takes place when the pair is born closer to the original vortex. Then the AV can be captured by the V and an annihilation with the original vortex happens; see Fig. 1d. The collision process is essentially inelastic. During the collision, the original vortex and the antivortex form a topological nontrivial pair ($Q = -1$), which performs a rotational motion around some guiding center. This rotating vortex dipole forms a localized skyrmin (Belavin–Polyakov soliton), which is stable in the continuum system. In the discrete lattice system the radius of this soliton, i.e., the distance between vortex and antivortex, decreases rapidly almost without energy loss. When the soliton radius is about one lattice constant, the pair undergoes the topologically forbidden annihilation, which is accompanied by strong spin-wave radiation, because the topological properties of the system change.

The three-body problem can be described analytically in a rigid vortex approach, based on Thiele-like equations (6):

$$2 \Omega_i [\mathbf{R}_i \times \dot{\mathbf{z}}] = \sum_{j \neq i} q_j q_i \frac{\mathbf{R}_i - \mathbf{R}_j}{|\mathbf{R}_i - \mathbf{R}_j|^2} + \mathbf{F}^{\text{ext}}_{ii} - \gamma \dot{\mathbf{R}}_i$$

where $\gamma$ is the damping constant.

Here $\mathbf{F}^{\text{ext}}_{ii}$ is the driving force (7), caused by the field $\mathbf{H}$ or spin-current $\mathbf{J}$ pumping. This three-body process in exchange interaction approximation has been studied in detail by Komineas and Papanicolaou. The set of Eqs. (9) describes the main features of the observed three-body dynamics. During the evolution, the original vortex and the antivortex create a rotating dipole, in agreement with Refs. 48 and 59; see Fig. 2. The distance in this vortex dipole rapidly tends to zero. The newborn vortex moves on a clockwise spiral to the origin.

**SUMMARY**

To summarize, we have studied the switching of the magnetic vortex polarity under the action of a rotating magnetic field and under the action of a spin-polarized current. The switching picture involving the creation and annihilation of a vortex-antivortex pair is very general and does not depend on the details how the vortex dynamics was excited. In particular, such a switching mechanism can be induced by a field pulse, by an ac oscillating rotating field, by an in-plane electrical current (inhomogeneous spin torque), and by a perpendicular current (homogeneous spin torque). Our analytical analysis is confirmed by numerical spin-lattice simulations.

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Magnetic skyrmion” and is widely used for the localized solitons, e.g., in 

other papers related to this topic. The energy of the magnetic skyrmion is described by the magnetic moment equation

\[ \mathbf{M} = \frac{\mathbf{M}_0}{2} \left( 1 - \frac{2}{3} \mathbf{S}^2 \right) \mathbf{S} \]

where \( \mathbf{M} \) is the magnetic moment, \( \mathbf{M}_0 \) is the saturation magnetization, and \( \mathbf{S} \) is the spin density. The magnetic skyrmion can be described as a topological soliton, i.e., a localized magnetic vortex, which is a non-trivial topological defect in the magnetization field.

The magnetic skyrmion has been observed in various magnetic materials, such as FeGe, PtMn, and MnIr, and its dynamics have been studied using micromagnetic simulations and experiments. The magnetic skyrmion can be excited using external magnetic fields, and its spin dynamics can be controlled using external electric fields or light pulses.

The magnetic skyrmion has potential applications in spintronics and magnetic memory devices. The magnetic skyrmion can be used as a magnetic data storage medium, with each skyrmion representing a bit of information.

The magnetic skyrmion is also a candidate for spintronic devices, such as magnetic tunnel junctions (MTJs), which can be used to switch the magnetization of the skyrmion, thus generating a current signal. The magnetic skyrmion can also be used in magnetic field sensors, magnetic random access memory (MRAM) devices, and magnetic logic devices.

In conclusion, the magnetic skyrmion is a fascinating magnetic object with potential applications in spintronics and magnetic memory devices. Further studies are needed to better understand its properties and to develop new applications based on this fascinating magnetic object.